

系统生物学

(Systems Biology)

马彬广





基因表达模型

(第十二讲)







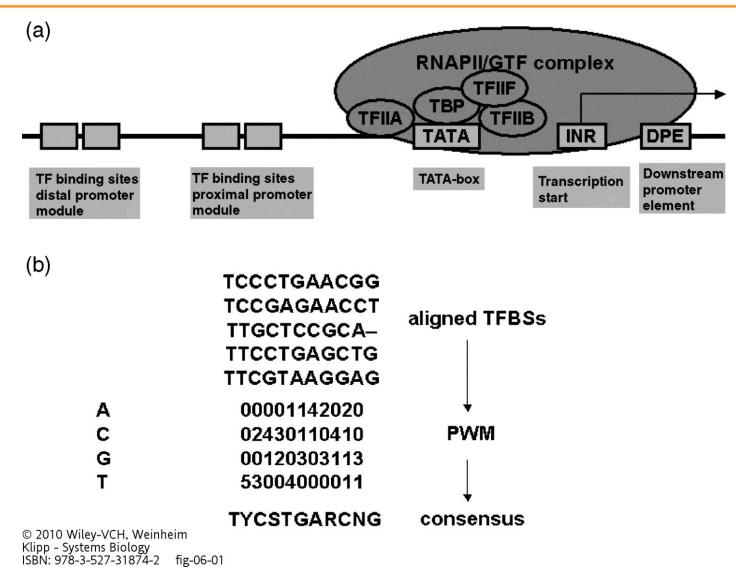
- □ Transcriptional control: when and how often is a gene transcribed.
- □ RNA processing control: how is the RNA transcript spliced.
- RNA transport and localization control: which mRNAs in the nucleus are exported to cytosol and where in the cytosol are they localized.
- □ Translational control: which mRNAs in the cytosol are translated by ribosomes.
- mRNA degradation control: which mRNAs in the cytosol are destroyed.
- Protein activity control: decide upon activation, inactivation, compartmentalization, degradation of the translated proteins.





真核基因启动子的一般结构

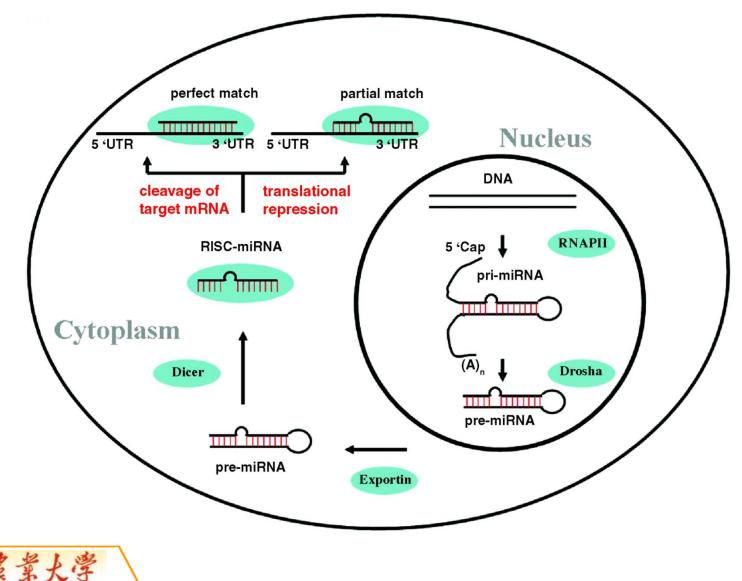








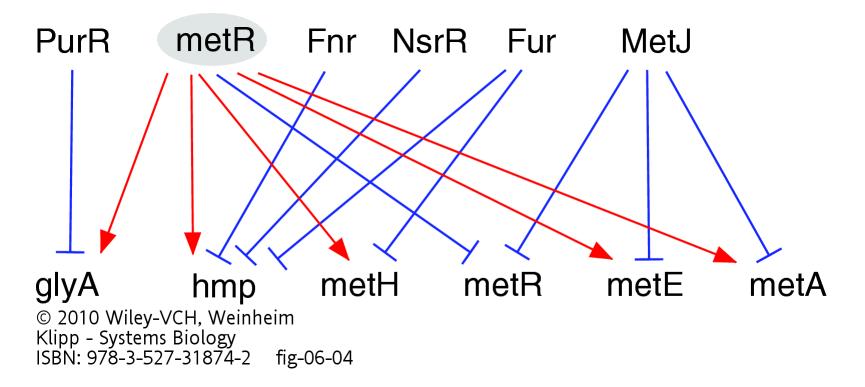




HUAZHONG AGRICULTURAL UNIVERSIT





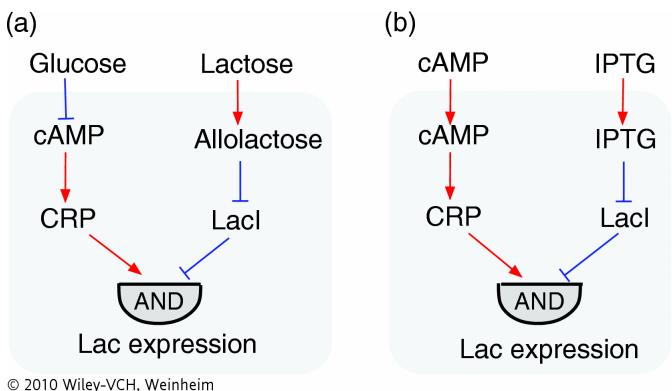


Genetic network in *E. coli* comprising the transcriptional regulator MetR and its known target genes. MetR (gray ellipse) regulates a number of target genes (bottom), which therefore form the MetR regulon. Other regulators controlling these genes are shown on top. Arrows denote transcriptional regulation (blue: repression, red: activation). Data taken from the EcoCyc database.









© 2010 Wiley-VCH, Weinheim Klipp - Systems Biology ISBN: 978-3-527-31874-2 fig-06-05

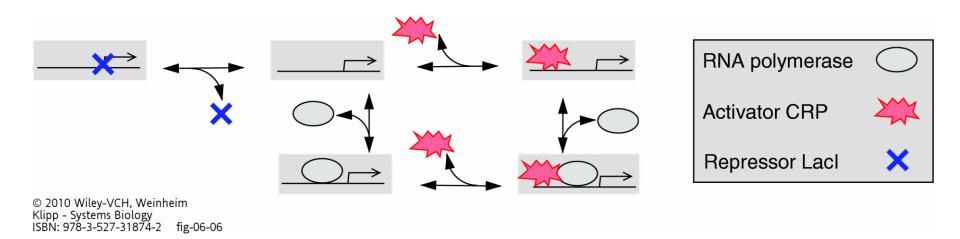
The Lac operon is controlled by the transcriptional regulators CRP and Lacl, which respond to extracellular levels of lactose and glucose. High expression of the Lac operon requires that lactose is present and glucose is absent.

In an experiment, the activities of CRP and LacI are regulated by extracellular levels of the ligands cAMP and IPTG. Effectively, both substances activate Lac expression.







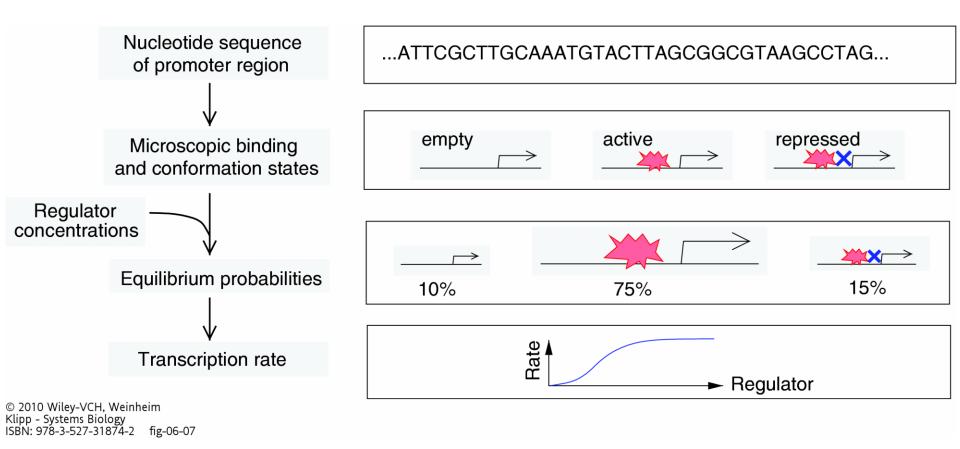


Microscopic states of the Lac promoter (schematic model). The promoter can be bound by RNA polymerase, the activator CRP, and the repressor Lacl. Bound activator increases the probability of polymerase binding (right). Transcription only occurs in states with bound polymerase (bottom). Bound repressor Lacl inhibits binding of other molecules (left). In reality, the promoter sequence is much more complex: Lacl can bind to several binding sites and cause DNA looping.









Schematic relation between nucleotide sequence and transcription rates.







一般形式:
$$y(t) = f(\mathbf{x}(t), \mathbf{p})$$

假设:

- 1. 在所考虑的时间尺度上,存在平衡态,且平衡态下,各微观状态出现的概率依赖于各调控因子的浓度和它们与DNA序列的结合能。
- 2. 在每种微观状态下,转录过程以一定的速率随机启动。

经推导得出:
$$y = \frac{\sum_{i}^{i} w_i v_i}{\sum_{i}^{i} w_i}, w_i = e^{-\frac{F_i}{K_B T}}, F_i = E_i - TS_i$$

在实际应用中,有时用线性关系来近似表达基因调控函数:

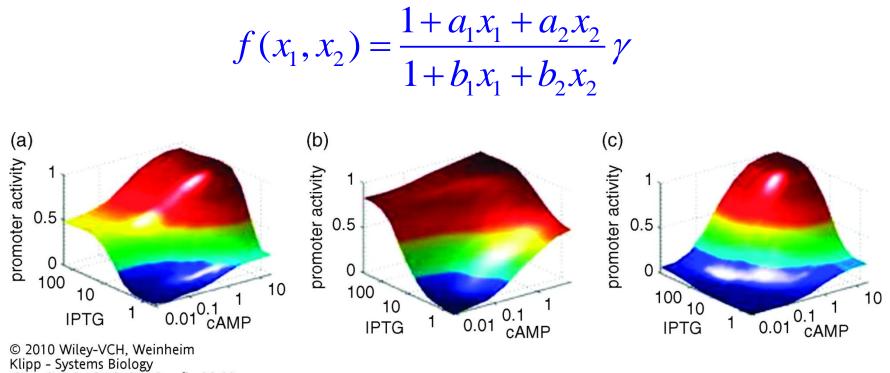
$$y_i(t) = \sum_l a_{il} x_l(t)$$

*i*表示当前的target gene,而*l*表示调控因子。









ISBN: 978-3-527-31874-2 fig-06-08

Gene regulation functions of the wild type Lac operon and two variants obtained by altered promoter sequences. Measured gene regulation function in an *E. coli* wild-type strain. The strain U340 (obtained from a screen of *E. coli* strains with point mutations in the Lac promoter) shows an OR-like regulation function. Another strain, U339, shows an AND-like regulation function. From PLoS Biol, 4: e45.







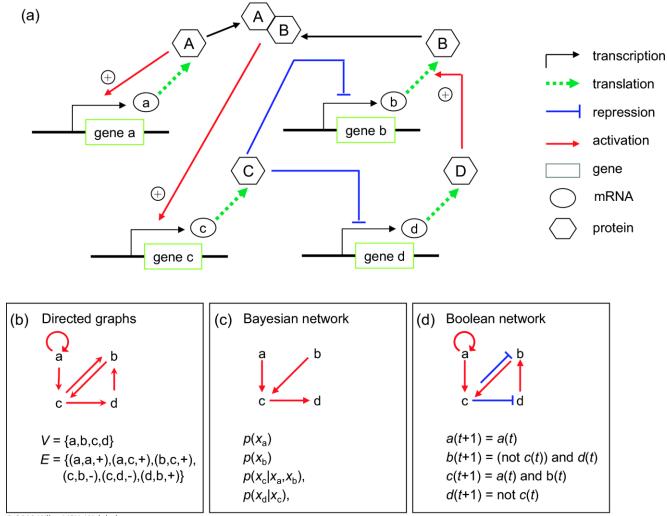
- **D** Directed Graph G = (V, E).
- Bayesian Network.
- Boolean Network.
- **D** ODE.
- □ Stochastic Process.





基因调控网络建模





© 2010 Wiley-VCH, Weinheim Klipp - Systems Biology ISBN: 978-3-527-31874-2 fig-06-09







Boolean Rules for a node with *K*=1 input

| Input | Output | | | | | | | |
|-------|--------|---|---|---|--|--|--|--|
| А | 0 | А | 1 | | | | | |
| 0 | 0 | 0 | 1 | 1 | | | | |
| 1 | 0 | 1 | 0 | 1 | | | | |
| Rule | 0 | 1 | 2 | 3 | | | | |

Boolean Rules for a node with *K*=2 inputs

| Inp | out | Output | | | | | | | | | | | | | | | |
|------|-----|--------|-----|---|---|---|---|-----|----|-----|---|------|----|------|----|------|----|
| А | В | 0 | AND | | А | | В | XOR | OR | NOR | | notB | | notA | | nAND | 1 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 |
| 1 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 |
| Rule | | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |







The network

 $A \to B \to C \to D$

has the maximal connectivity K = 1.

Let A = const., B = $f_B(A)$ = not A, C = $f_C(B)$ = not B, D = $f_D(C)$ = C with the initial state (A, B, C, D)(t_0) = (1, 0, 0, 0).

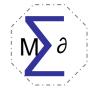
The following states are

(A, B, C, D) $(t_1) = (1, 0, 1, 0)$ (A, B, C, D) $(t_2) = (1, 0, 1, 1)$ (A, B, C, D) $(t_3) = (1, 0, 1, 1)$

 $(A, B, C, D)(t_i) = (1, 0, 1, 1) \text{ for } i = 2, ..., \infty$

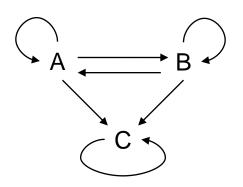
After two steps, the system has attained a fixed point.







The network



has 3 elements and $2^3 = 8$ states. Let the rules be

A(t+1) = A(t) and B(t) B(t+1) = A(t) or B(t)C(t+1) = A(t) or (not B(t) and C(t))

The Table below lists the successive states.

| Successive states for the above Boolean network | | | | | | | | |
|---|-----|-----|-----|-----|-----|-----|-----|-----|
| Current state | 000 | 001 | 010 | 011 | 100 | 101 | 110 | 111 |
| Next state | 000 | 001 | 010 | 010 | 011 | 011 | 111 | 111 |

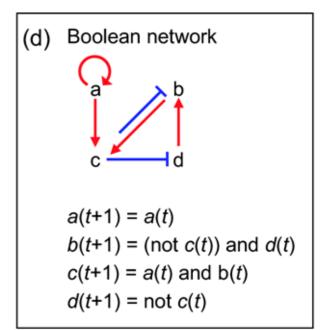
Fixed points: (000), (001), (010), (111);



Unreachable states from other state: (000), (001), (100), (101), (110).







Apply the flowing Boolean rules

 $a(t+1) = f_a(a(t)) = a(t)$ $b(t+1) = f_b(c(t), d(t)) = \text{not } c(t) \text{ and } d(t)$ $c(t+1) = f_c(a(t), b(t)) = a(t) \text{ and } b(t)$ $d(t+1) = f_d(c(t)) = \text{not } c(t)$

The temporal behavior is determined by the successive states as follows.

 $(0000) \rightarrow (0001), (0001) \rightarrow (0101), (0010) \rightarrow (0000), (0011) \rightarrow (0000),$ $(0100) \rightarrow (0001), (0101) \rightarrow (0101), (0110) \rightarrow (0000), (0111) \rightarrow (0000),$ $(1000) \rightarrow (1001), (1001) \rightarrow (1101), (1010) \rightarrow (1000), (1011) \rightarrow (1000),$ $(1100) \rightarrow (1011), (1101) \rightarrow (1111), (1110) \rightarrow (1010), (1111) \rightarrow (1010).$







□ Start from 0: the system evolves to a steady state 0101;

□ Start from 1: the system evolves toward a cyclic behavior of the following state sequence: $1000 \rightarrow 1001 \rightarrow 1101 \rightarrow 1111 \rightarrow 1010 \rightarrow 1000$.

The above steady states are called attractors, and other states are transient states.

Kauffman revealed that the median number of attractors and the cycle length of the attractors are proportional to sqrt(N), N is the number of system components.

Kauffman suggested to interpret the number of possible attractors as the number of possible cell types arising from the same genome.

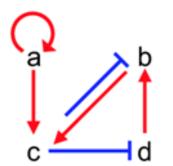
Ref: Journal of Theoretical Biology, 149: 467-505. and JTB 173: 427-440.





基因调控网络建模(ODE)





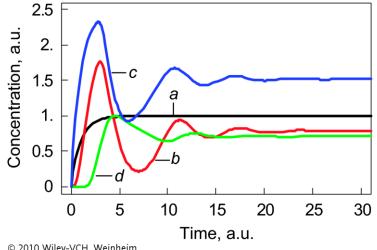
$$\frac{da}{dt} = f_a(a) = v_a - k_a \cdot a$$

$$\frac{db}{dt} = f_b(b, c, d) = \frac{V_b \cdot (d / K_b)^{n_d}}{(1 + (d / K_b)^{n_d})(1 + (c / K_{lc})^{n_c})} - k_b \cdot b$$

$$\frac{dc}{dt} = f_c(a, b, c) = \frac{V_c \cdot (a \cdot b / K_c)^{n_{ab}}}{1 + (a \cdot b / K_c)^{n_{ab}}} - k_c \cdot c$$

$$\frac{dd}{dt} = f_d(c, d) = \frac{V_d}{1 + (c / K_{lc})^{n_c}} - k_d \cdot d$$

Dynamics of the mRNA concentrations of the system. Parameters: va = 1, ka = 1, vb = 1, Kb = 5, klc = 0.4, Kb = 0.1, Vc = 1, Kc = 5, Kc = 0.1, Vd = 1, kd = 1, nab = 4, nc = 4, nd = 4. Initial conditions: a(0) = b(0) = c(0) = d(0) = 0.



© 2010 Wiley-VCH, Weinheim Klipp - Systems Biology ISBN: 978-3-527-31874-2 fig-06-11





ODE建模的局限性



□ ODE是变量连续变化的模型。但在实际的系统中,有些量是不连续的,连续变化只是一个近似。

□ ODE是确定性的模型,没有考虑随机性,而在真实的系统中,随 机性大量存在。

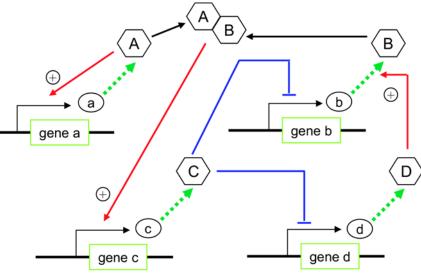
□ 分子系统中不连续的例子:分子数目,特变是转录因子的拷贝数可能很低,事件过程也可以步进的方式变化。

□ 随机性的例子: 热运动、细胞内部状态的随机涨落、来自外部环 境的随机因素等。



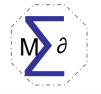






| 華. | ト震 | 書 | K | 學 | |
|--------|-----------|--------|-------|--------|--|
| HUAZHO | NG AGRICI | ULTURA | LUNIV | ERSITY | |

| Expression of protein A from gene a, | $a \to a + A,$ | $k_{\rm A} = 1.0$ |
|--------------------------------------|-----------------------------------|--------------------|
| Expression of protein B from gene b, | $b \rightarrow b + B$, | $k_{\rm B} = 1.0$ |
| Expression of protein C from gene c, | $c \rightarrow c + C$, | $k_{\rm C} = 0.2$ |
| Expression of protein D from gene d, | $d \rightarrow d + D$, | $k_{\rm D} = 1.0$ |
| Formation of protein complex AB, | $A + B \rightarrow AB$, | $k_{AB} = 1.0$ |
| Inhibition of gene b | $b + C \rightarrow b_1 + C$, | $k_{\rm bl} = 1.0$ |
| Activation of gene b, | $b_I \mathop{\longrightarrow} b,$ | $k_{\rm bA} = 0.1$ |
| Inhibition of gene c, | $c \mathop{\rightarrow} c_{1},$ | $k_{cl} = 0.1$ |
| Activation of gene c, | $c_I + AB \rightarrow c + AB,$ | $k_{cA} = 1.0$ |
| Inhibition of gene d, | $d + C \rightarrow d_1 + C$, | $k_{\rm dl} = 1.0$ |
| Activation of gene d, | $d_{I} \rightarrow d,$ | $k_{\rm dA} = 0.1$ |
| Degradation of protein A, | $A \rightarrow$, | $k_{\rm Ad} = 1.0$ |
| Degradation of protein B, | $B \to ,$ | $k_{\rm Bd} = 0.1$ |
| Degradation of protein C, | $C \rightarrow$, | $k_{\rm Cd} = 1.0$ |
| Degradation of protein D, | $D \rightarrow$, | $k_{\rm Dd} = 1.0$ |
| Degradation of protein complex AB, | $AB \rightarrow$, | $k_{ABd} = 1.0$ |
| | | |





Stochastic simulations of the reaction network shown in Figure using the system .

(a) Individual simulation run,

(b) average over 100 simulation runs, both simulated with Gillespie's direct method, and (c) deterministic simulation. Parameters: see text, initial abundances: gene a = 10; protein A = 0; gene b = 10; gene bi = 0; protein B = 0; gene c = 0; gene ci = 10; protein C = 0; gene d = 10; gene di = 0; protein D = 0; complex AB = 0.

